

**Warsaw University
of Technology**



**Faculty of Power and
Aeronautical Engineering**

WARSAW UNIVERSITY OF TECHNOLOGY

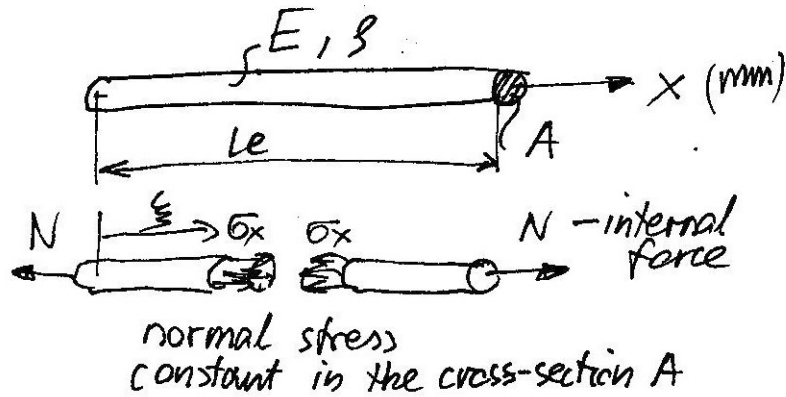
Institute of Aeronautics and Applied Mechanics

Finite element method (FEM)

Bar finite element

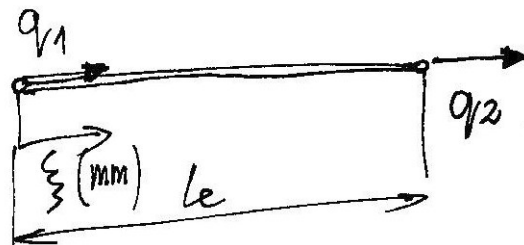
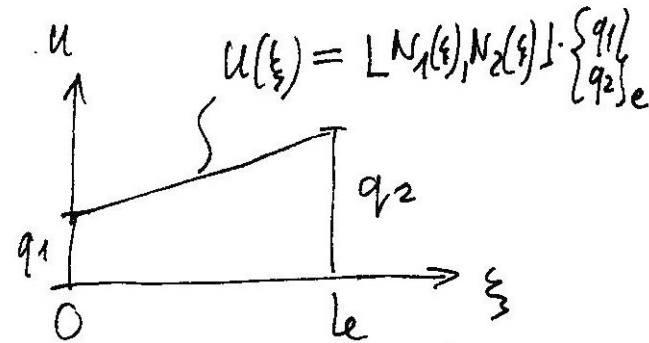
04.2021

A bar finite element (1D)



ξ - local coordinate

$$d\xi = dx$$



shape functions: $N_1(\xi) = 1 - \frac{\xi}{Le}$
 $N_2(\xi) = \frac{\xi}{Le}$

$$E_x = \frac{du}{dx} = \frac{du}{d\xi} \frac{d\xi}{dx} = \frac{d([N_1, N_2]) \cdot \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix}_e}{d\xi} =$$

$$= \frac{d([N_1, N_2])}{d\xi} \cdot \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix}_e + \frac{d \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix}_e}{d\xi} \cdot [N_1, N_2] = \underbrace{\frac{d \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix}_e}{d\xi}}_{=0} \cdot [N_1, N_2] = \underbrace{\frac{dN_1}{d\xi}, \frac{dN_2}{d\xi}}_{=0} \cdot \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix}_e =$$

$$\left. \begin{aligned} \epsilon_x &= -\frac{1}{l_e} \cdot q_1 + \frac{1}{l_e} \cdot q_2 = \frac{q_2 - q_1}{l_e} \\ \sigma_x &= E \epsilon_x = \frac{E(q_2 - q_1)}{l_e} \\ N &= \sigma_x \cdot A = \frac{EA}{l_e} (q_2 - q_1) \end{aligned} \right\} = \text{const in the finite element}$$

elastic strain energy:

$$\begin{aligned} U_e &= \frac{1}{2} \int_{S_e} \sigma_x \epsilon_x dS_e = \frac{1}{2} \int_0^{l_e} \sigma_x \epsilon_x \int_A dA dx = \frac{EA}{2} \int_0^{l_e} \frac{du}{d\xi} \cdot \frac{du}{d\xi} d\xi = \\ &= \frac{1}{2} \underset{1 \times 2}{L} \underset{0}{q} \underset{EA}{l_e} \int_0^{l_e} \begin{bmatrix} \frac{dN_1}{d\xi} & \frac{dN_1}{d\xi} & \frac{dN_2}{d\xi} & \frac{dN_2}{d\xi} \\ \frac{dN_2}{d\xi} & \frac{dN_1}{d\xi} & \frac{dN_2}{d\xi} & \frac{dN_1}{d\xi} \end{bmatrix} d\xi \cdot \underset{2 \times 1}{\{q\}_e} = \underset{0}{L} \underset{EA}{l_e} \cdot \begin{Bmatrix} \frac{dN_1}{d\xi} \\ \frac{dN_2}{d\xi} \end{Bmatrix} \cdot \begin{bmatrix} \frac{dN_1}{d\xi} & \frac{dN_2}{d\xi} \end{bmatrix} \cdot \underset{1 \times 1}{\{q\}_e} \end{aligned}$$

$$U_e = \frac{1}{2} L q_e \cdot EA \begin{bmatrix} \int_0^L \left(-\frac{1}{L}\right)\left(\frac{1}{L}\right) d\xi & \int_0^L \left(-\frac{1}{L}\right)\left(\frac{1}{L}\right) d\xi \\ \int_0^L \left(\frac{1}{L}\right)\left(-\frac{1}{L}\right) d\xi & \int_0^L \left(\frac{1}{L}\right)\left(\frac{1}{L}\right) d\xi \end{bmatrix} \cdot \{q\}_e =$$

$$= \frac{1}{2} L q_e \cdot \underbrace{\frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}}_{\text{local stiffness matrix } [k]_e} \cdot \{q\}_e = \frac{1}{2} L q_e [k]_e \{q\}_e$$

potential energy of loading due to mass forces:

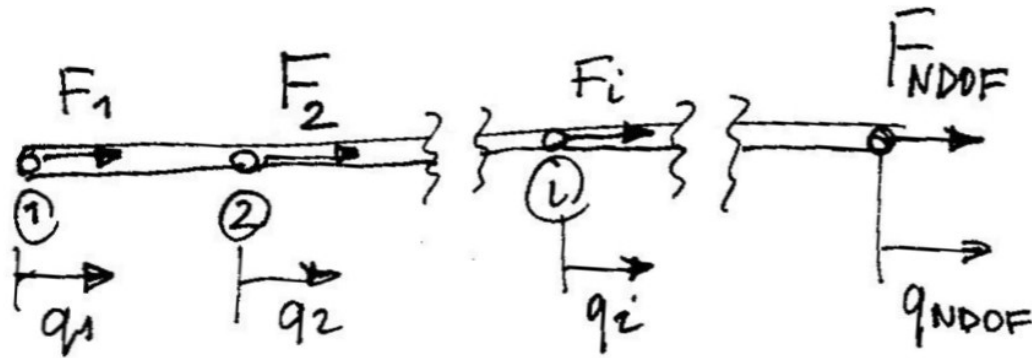
$$\begin{aligned}
 W_e &= \int_{S_e} [X] \cdot \{u\} dS_e = \int_{S_e} g(\alpha_x \cdot u + \alpha_y \cdot v + \alpha_z \cdot w) dS_e = \\
 &= \int_0^l g \alpha_x \cdot u \int_A dA d\xi = \int_0^l \underbrace{g A \alpha_x \cdot u}_{\text{traction } p(\xi) \left(\frac{N}{m}\right)} d\xi = \int_0^l p(\xi) u d\xi =
 \end{aligned}$$

$$= \int_0^l p(\xi) \cdot [N]_{1 \times 2} \cdot \{q\}_e^{2 \times 1} d\xi = \underbrace{\left[\int_0^l p(\xi) \cdot N_1 d\xi \right]}_{F_{1e}} \cdot \underbrace{\left[\int_0^l p(\xi) \cdot N_2 d\xi \right]}_{F_{2e}} \cdot \{q\}_e^{2 \times 1} =$$

$$= [F]_e \cdot \{q\}_e$$

equivalent
load vector

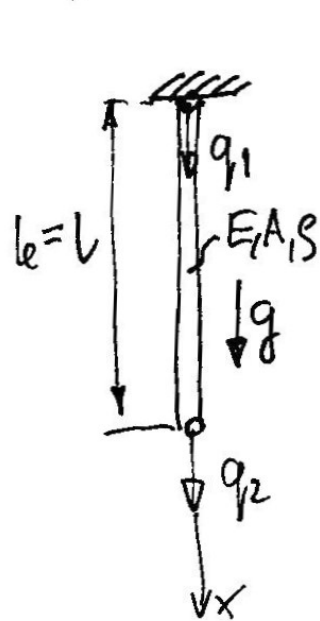
potential energy of nodal loads



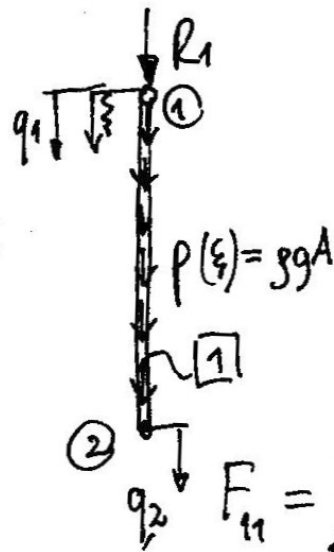
$$W^n = \sum_{i=1}^{NDOF} F_i q_i$$

Example. Find displacement, strain and stress in a finite element model of a bar loaded by gravity. Use one and two FEs. Compare a FE solution with an exact solution and the Ritz solution.

1°) one finite element:



$$\xi = x$$



$$\{q\}_1 = \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix}_1, \quad \{q\} = \{q\}_1$$

$$[k]_1 = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = [K] = [k]_1^*$$

$$[F]_1 = [F_{11}, F_{21}]$$

$$F_{11} = \int_0^L p N_1(\xi) d\xi = \rho g A \int_0^L \left(1 - \frac{\xi}{L}\right) d\xi = \rho g A \left(\xi - \frac{\xi^2}{2L}\right) \Big|_0^L = \frac{\rho g A L}{2}$$

$$F_{21} = \int_0^L p N_2(\xi) d\xi = \frac{\rho g A L}{2}, \quad [F]^e = [F]_1 = [F]_1^*$$

$$\{F\}_{1 \times 2}^n = \{R_1, 0\}, \quad \{F\}_{1 \times 2} = \{F\}_{1 \times 2}^e + \{F\}_{1 \times 2}^n = \left\{ \frac{\rho g A L}{2} + R_1, \frac{\rho g A L}{2} \right\}$$

$$\begin{matrix} [K] & \cdot & \{q\} & = & \{F\} \\ 1 \times 2 & & 2 \times 1 & & 2 \times 1 \end{matrix} \Rightarrow \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \cdot \begin{Bmatrix} q_1 \\ q_2 \end{Bmatrix} = \begin{Bmatrix} \frac{\rho g A L}{2} + R_1 \\ \frac{\rho g A L}{2} \end{Bmatrix}$$

+ boundary condition $q_1 = 0$

$$\frac{EA}{L} \cdot q_2 = \frac{\rho g A L}{2} \Rightarrow q_2 = \frac{\rho g L^2}{2E}$$

displacement in the element:

$$u(\xi) = u(x) = \{N\} \cdot \{q\}_{1,2} = N_1 \cdot q_1 + N_2 \cdot q_2 = \frac{\xi}{L} \frac{\rho g L^2}{2E} = \frac{\rho g L}{2E} \cdot \xi$$

strain in the element:

$$\epsilon_x = \frac{q_2 - q_1}{L} = \frac{\rho g L}{2E} = \text{const.}$$

stress in the element:

$$\sigma_x = E \epsilon_x = \frac{\rho g L}{2} = \text{const.}$$

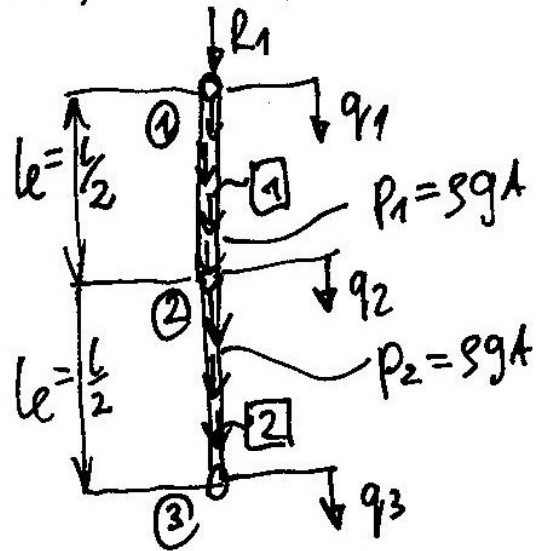
reaction:

$$\frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \cdot \begin{Bmatrix} 0 \\ \frac{sgL^2}{2E} \end{Bmatrix} = \begin{Bmatrix} \frac{sgAL}{2} + R_1 \\ \frac{sgAL}{2} \end{Bmatrix}$$

$$\frac{EA}{L} \left(1 \cdot 0 - 1 \cdot \frac{sgL^2}{2E} \right) = \frac{sgAL}{2} + R_1$$

$$R_1 = -\frac{sgAL}{2} - \frac{sgAL}{2} = -sgAL = -m \cdot g$$

2^o) two finite elements:



$$\begin{cases} q \end{cases}_1 = \begin{cases} q_1 \\ q_2 \end{cases}_1$$

$$\begin{cases} q \end{cases}_2 = \begin{cases} q_2 \\ q_3 \end{cases}_2$$

$$\begin{cases} q \end{cases} = \begin{cases} q_1 \\ q_2 \\ q_3 \end{cases}$$

$$[K]_1 = \frac{2EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$[K]_1^* = \frac{2EA}{L} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$[K]_2 = \frac{2EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$[K]_2^* = \frac{2EA}{L} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

$$[K] = [K]_1^* + [K]_2^* = \frac{2EA}{L} \begin{bmatrix} 1 & -1 & 0 \\ 1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

$$\det [K] = 0$$

$$[F]_1 = \begin{bmatrix} \int_0^{\frac{L}{2}} P_1 N_1 d\xi, & \int_0^{\frac{L}{2}} P_1 N_2 d\xi \end{bmatrix} = \frac{3qAL}{4} [1, 1]$$

$$[F]_2 = \begin{bmatrix} \int_0^{\frac{L}{2}} P_2 N_1 d\xi, & \int_0^{\frac{L}{2}} P_2 N_2 d\xi \end{bmatrix} = \frac{3qAL}{4} [1, 1] \quad ; \quad [F]_1^* = \frac{3qAL}{4} [1, 1, 0]$$

$$[F]^e = \sum_{e=1}^2 [F]_e^* = [F]_1^* + [F]_2^* = \frac{3qAL}{4} [1, 2, 1]$$

$$; \quad [F]_2^* = \frac{3qAL}{4} [0, 1, 1]$$

$$[F]^n = [R_1, 0, 0] \quad , \quad [F] = \left[R_1 + \frac{3qAL}{4}, \frac{3qAL}{2}, \frac{3qAL}{4} \right]$$

$$[K] \cdot \{q\} = \{F\}$$

$\begin{matrix} 3 \times 3 & 3 \times 1 & 3 \times 1 \end{matrix}$

$$\frac{2EA}{L} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \cdot \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \end{Bmatrix} = \begin{Bmatrix} R_1 + \frac{3qAL}{4} \\ \frac{3qAL}{2} \\ \frac{3qAL}{4} \end{Bmatrix}$$

+ boundary condition $q_1 = 0$

$$\underbrace{\frac{2EA}{L} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}}_{[K]_{2 \times 2}} \cdot \begin{Bmatrix} q_2 \\ q_3 \end{Bmatrix} = \begin{Bmatrix} \frac{pgAl}{2} \\ \frac{pgAl}{4} \end{Bmatrix}$$

$$\det [K]_{2 \times 2} = \left(\frac{2EA}{L}\right)^2 \cdot (2 \cdot 1 - (-1) \cdot (-1)) = \left(\frac{2EA}{L}\right)^2$$

$$[K^C]_{2 \times 2} = \frac{2EA}{L} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = [K]^T_{2 \times 2}$$

$$[K]^{-1} = \frac{1}{\det [K]_{2 \times 2}} \cdot [K^C]_{2 \times 2}^T = \frac{L}{2EA} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\begin{Bmatrix} q_2 \\ q_3 \end{Bmatrix} = [K]^{-1} \cdot \frac{pgAl}{4} \begin{Bmatrix} 2 \\ 1 \end{Bmatrix} = \frac{pgAl^2}{8EA} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} 2 \\ 1 \end{Bmatrix} = \frac{pgl^2}{8E} \begin{Bmatrix} 3 \\ 4 \end{Bmatrix}$$

$$q_2 = \frac{3}{8} \frac{pgl^2}{E} ; \quad q_3 = \frac{pgl^2}{2E}$$

displacements in elements : FE solution in elements:

$$\boxed{1} : u_1(\xi) = \underset{1 \times 2}{[N]} \cdot \underset{2 \times 1}{\{q\}_1} = \left(1 - \frac{\xi}{2}\right) \cdot q_1 + \left(\frac{\xi}{2}\right) \cdot q_2 =$$

$$= \frac{2\xi}{L} \cdot \frac{3}{8} \frac{\rho g L^2}{E} = \frac{3\rho g L}{4E} \cdot \xi$$

$$x \in \left(0, \frac{L}{2}\right); \quad \xi = x \Rightarrow u(x) = \frac{3\rho g L}{4E} \cdot x$$

$$u(0) = 0, \quad u\left(\frac{L}{2}\right) = \frac{3}{8} \frac{\rho g L^2}{E}$$

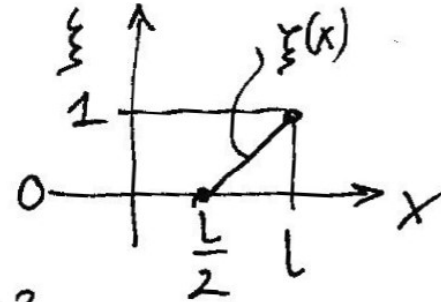
$$\epsilon_{x_1} = \left[\frac{dN_1}{d\xi}, \frac{dN_2}{d\xi} \right] \cdot \underset{2 \times 1}{\{q\}_1} = -\frac{2}{L} \cdot q_1 + \frac{2}{L} \cdot q_2 = \frac{3\rho g L}{4E}$$

$$\sigma_{x_1} = E \epsilon_{x_1} = \frac{3\rho g L}{4}$$

$$\boxed{2} \quad u_2(\xi) = \begin{bmatrix} N_1 \\ N_2 \end{bmatrix}_{1 \times 2} \cdot \begin{Bmatrix} q_2 \\ q_3 \end{Bmatrix}_{2 \times 1} = \left(1 - \frac{2\xi}{L}\right) q_2 + \frac{2\xi}{L} \cdot q_3 =$$

$$= \frac{3}{8} \frac{\rho g L^2}{E} - \frac{3 \rho g L}{4E} \cdot \xi + \frac{\rho g L}{E} \cdot \xi = \frac{\rho g L}{4E} \cdot \xi + \frac{3 \rho g L^2}{8E}$$

$$x \in \left\langle \frac{L}{2}, L \right\rangle ; \quad \xi(x) = x - \frac{L}{2}$$



$$u_2(x) = \frac{\rho g L}{4E} \cdot x + \frac{\rho g L^2}{4E} = \frac{\rho g}{4E} (x \cdot L + L^2)$$

$$u\left(\frac{L}{2}\right) = \frac{3}{8} \frac{\rho g L^2}{E}, \quad u(L) = \frac{\rho g L^2}{2E}$$

$$\epsilon_{x_2} = \begin{bmatrix} \frac{dN_1}{d\xi} & \frac{dN_2}{d\xi} \end{bmatrix} \cdot \begin{Bmatrix} q_2 \\ q_3 \end{Bmatrix} = -\frac{2}{L} q_2 + \frac{2}{L} q_3 = \frac{2(q_3 - q_2)}{L} = \frac{\rho g L}{4E}$$

$$\sigma_{x_2} = E \epsilon_{x_2} = \frac{\rho g L}{4}$$

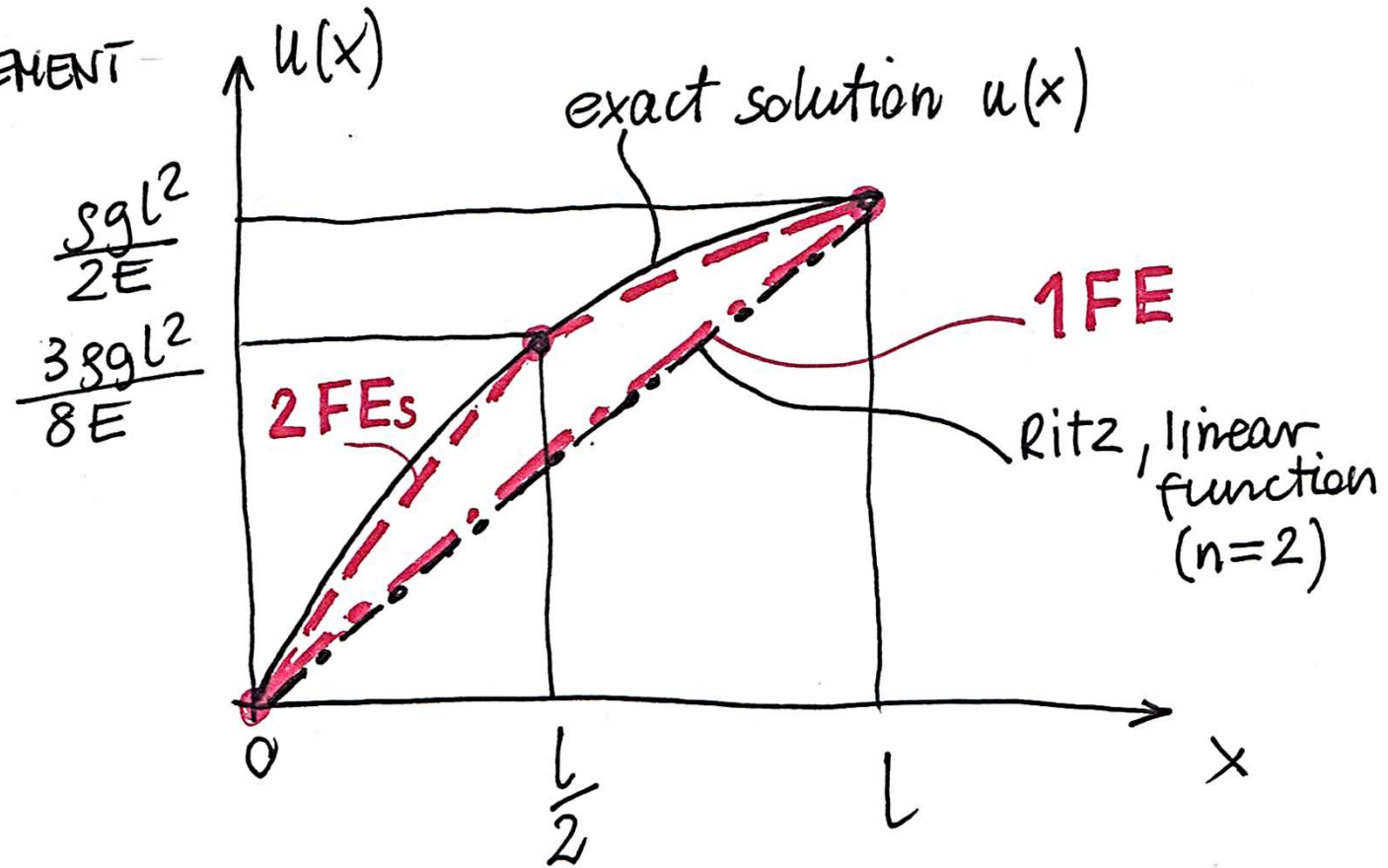
$$\text{reaction: } \frac{2EA}{L} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \cdot \frac{\rho g l^2}{8E} \begin{Bmatrix} 0 \\ 3 \\ 4 \end{Bmatrix} = \begin{Bmatrix} R_1 + \frac{\rho g AL}{4} \\ \vdots \\ \vdots \end{Bmatrix}$$

$$\frac{2EA}{L} (1 \cdot 0 - 1 \cdot 3 + 0 \cdot 4) \cdot \frac{\rho g l^2}{8E} = R_1 + \frac{\rho g AL}{4}$$

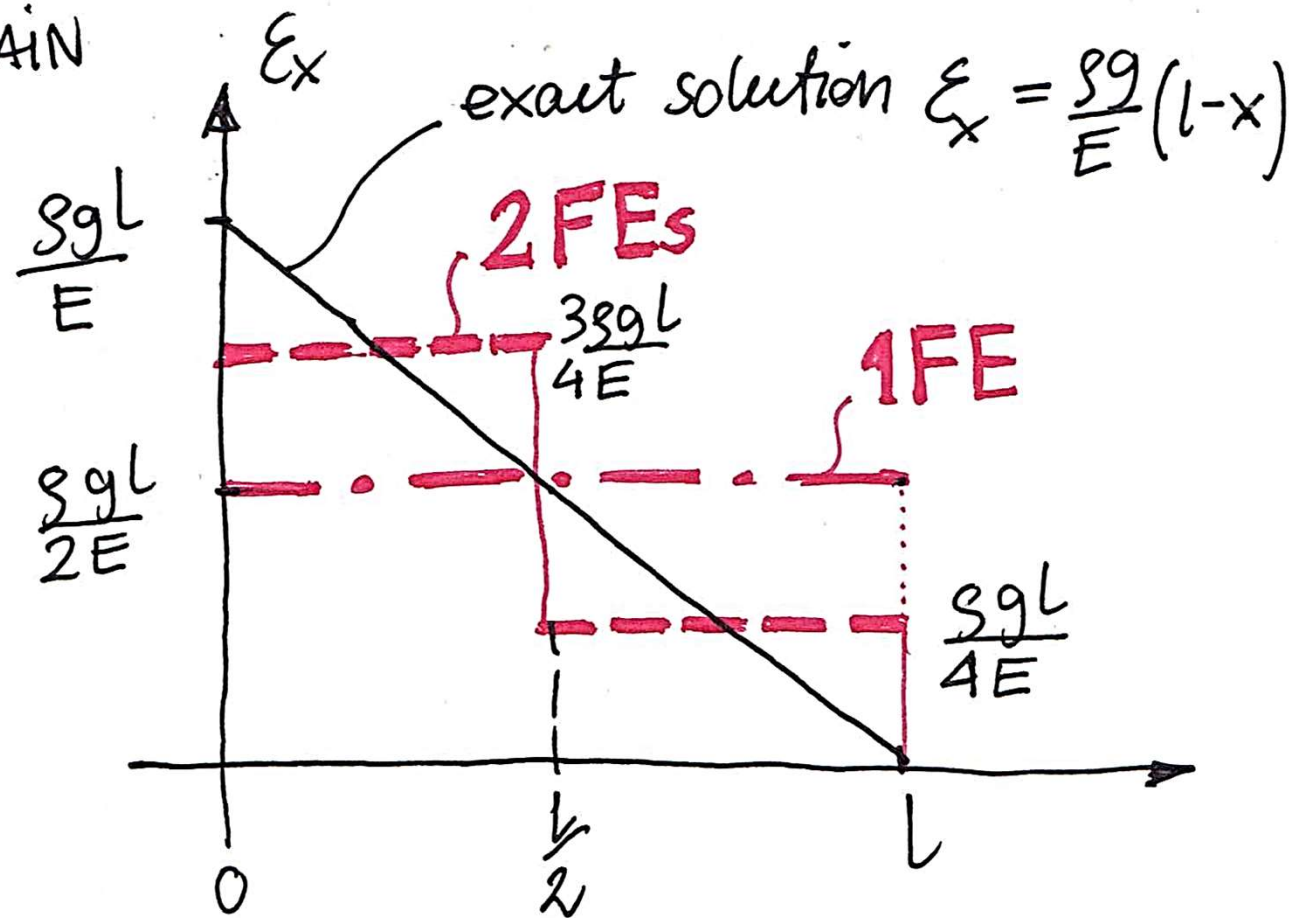
$$-\frac{3}{4} \rho g AL - \frac{1}{4} \rho g AL = R_1$$

$$R_1 = -\rho g AL = -mg$$

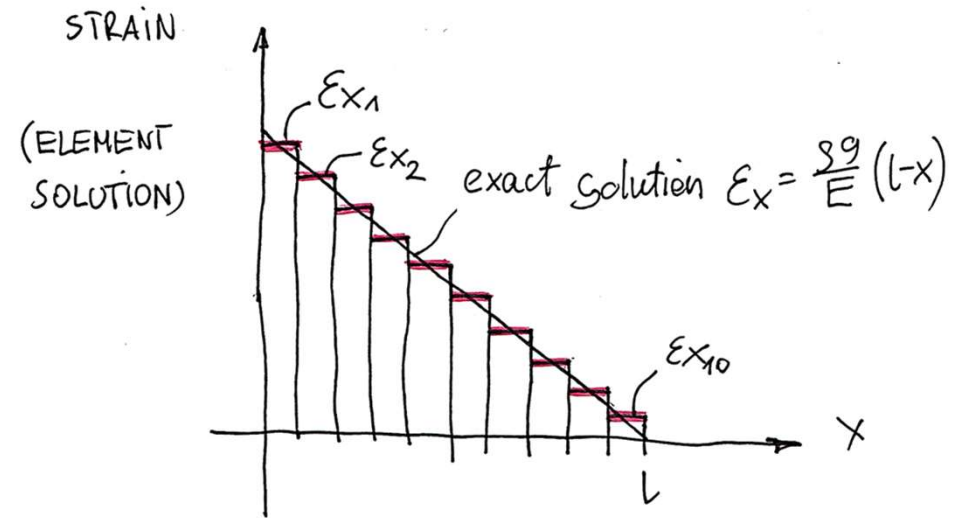
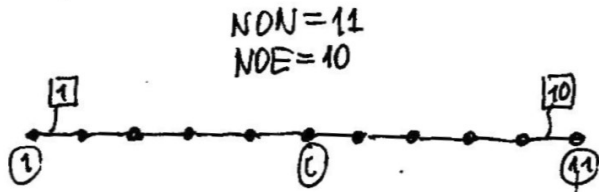
DISPLACEMENT



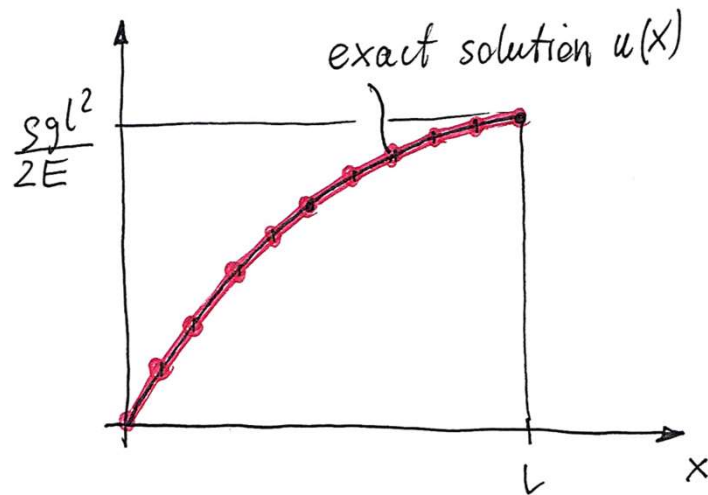
STRAIN



10 finite elements



DISPLACEMENT



STRAIN
(NODAL SOLUTION)

